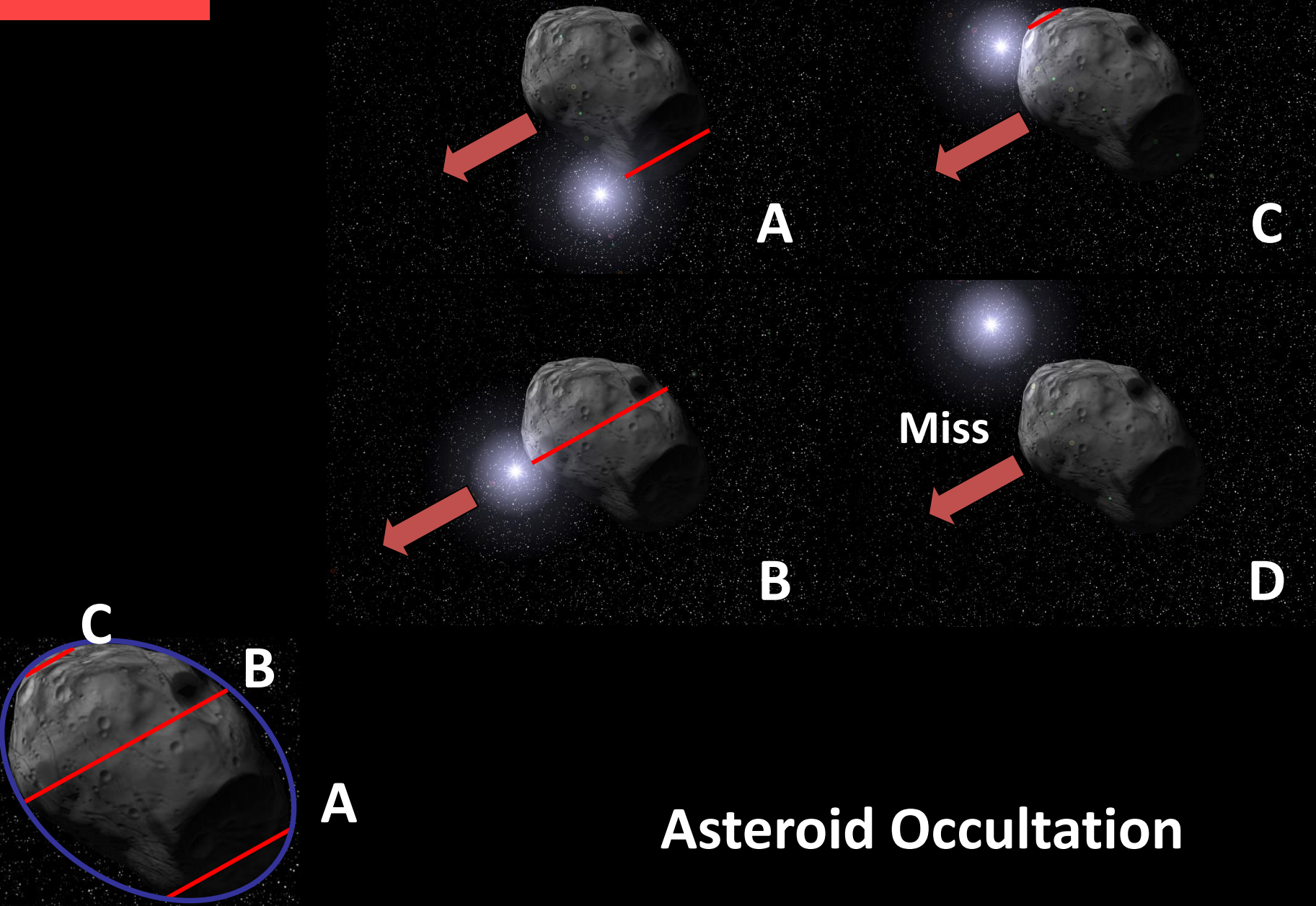


Timing Issues in occultations using a PC

Cesar VALENCIA GALLARDO, Ph.D.
TimeBox CEO and Founder

IOTA-ES, 38th European Symposium on Occultation Projects (ESOP 2019).
30th August-1st September 2019. Observatoire de Paris. Paris, FRANCE



Asteroid Occultation

Asteroid occultations present great qualities:

- Direct measure.
- Precise angular resolution.
- Available for Amateurs (Moderate cost and Freeware for predictions and analysis).

To correctly perform an asteroid occultations you need:

- Prediction (Occult, OccultWatcher, Steve Peston website, Euraster, etc.)
- Telescope.
- Camera (analogic/digital) → Produce linear photometry (Raw/untreated images).
- **Method to correctly date your recording with a standard time base → UTC = Universal Time.**

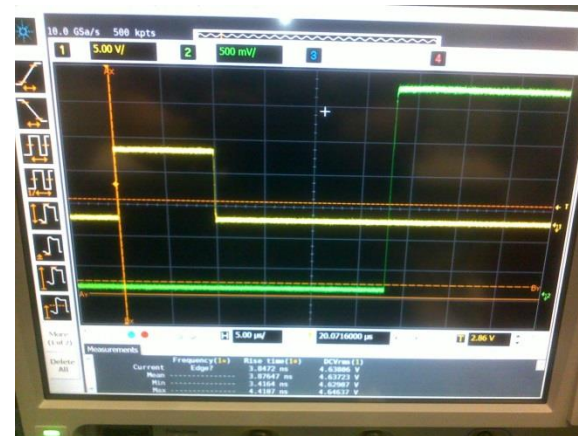
UTC time in astronomy

Get the UTC (Coordinated Universal Time) from GPS satellites with great precision (**$\pm 1000\text{-}200\text{nSec}$ UTC, 1PPS**).

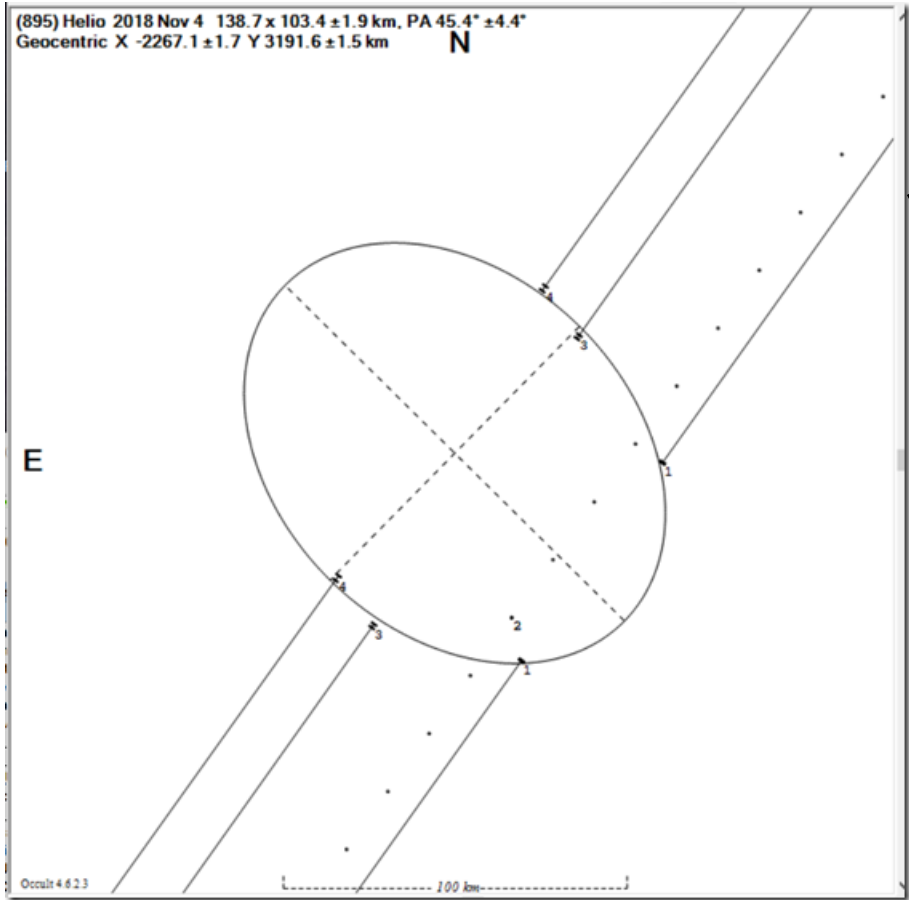
Astronomy

- Astrometry.
- PHEMU's.
- Occultations (Asteroid, TNO, Planets and Moon)
- Pulsar timing.

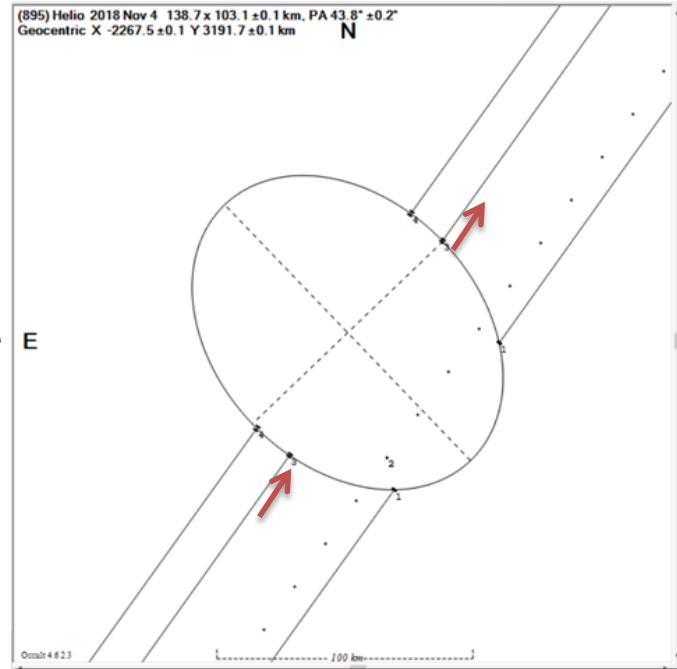
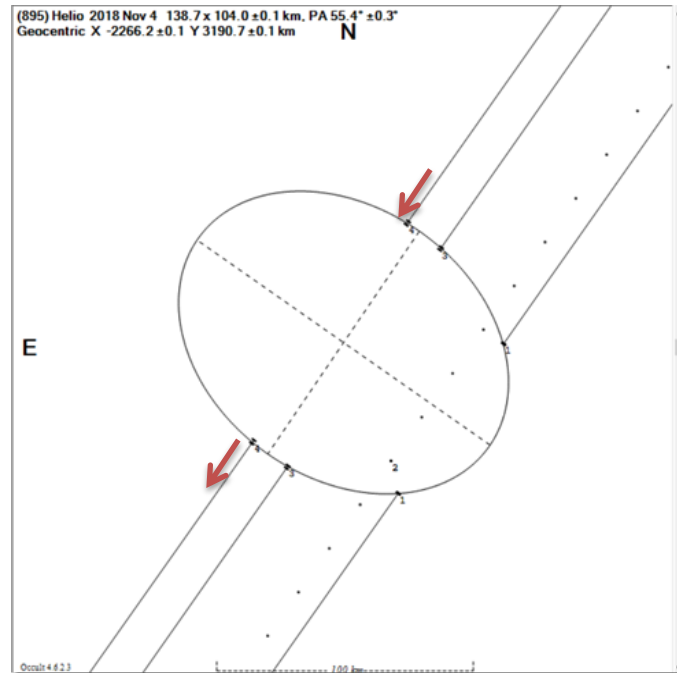
PC time synchronization.



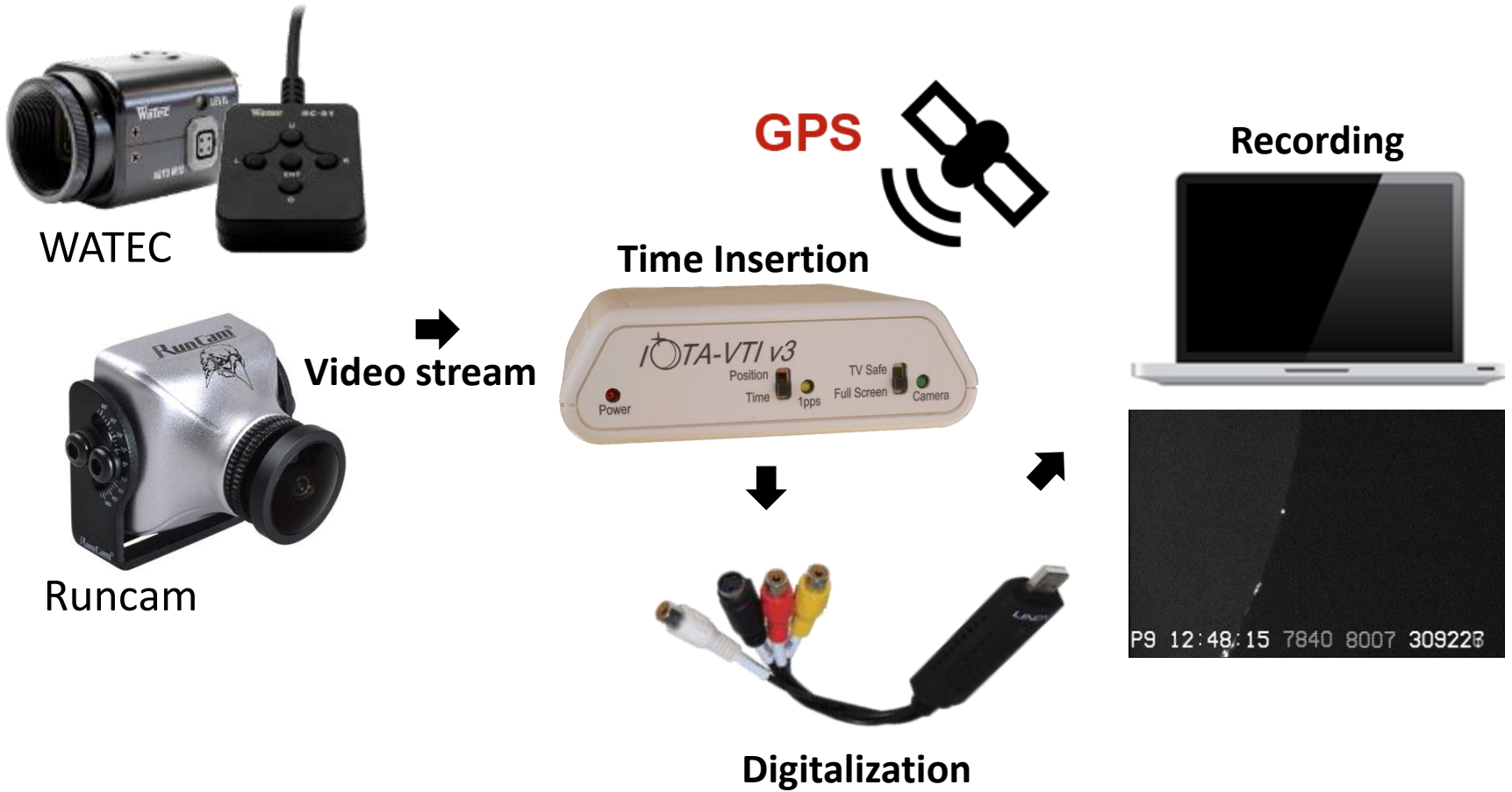
SYRTE (CNRS, Observatoire de Paris) Atomic Clock tests.



?



Analog recording with Time Inserter



Issues with the Analogic recording:

- **Availability** of latest sensitive and low noise image sensors (Sony STARVIS, sCMOS, EMCCD, etc.) → Lower image quality and higher noise.
- Lower Frame rates selection and **recording parameters** → Binning, Gain/EM Gain, ROI, etc.
- Possible image quality **degradation** before digitalization (cabling).

UTC precision timing using Digital video devices

Most amateur CCD and CMOS Cameras are **digital** → Planetary imaging, Autoguiding, etc...



Basler



TIS (DMK)



IDS



ZWO

New CMOS image sensors and Cameras arriving in the market! → **Digital**



Raptor Kite
EMCCD



Andor Neo
5.5 sCMOS



Photonics
Evolve
EMCCD

AiryLab

Genika (Windows)

~90.5% Windows

~7.72% Mac OS X

~1.74% Linux

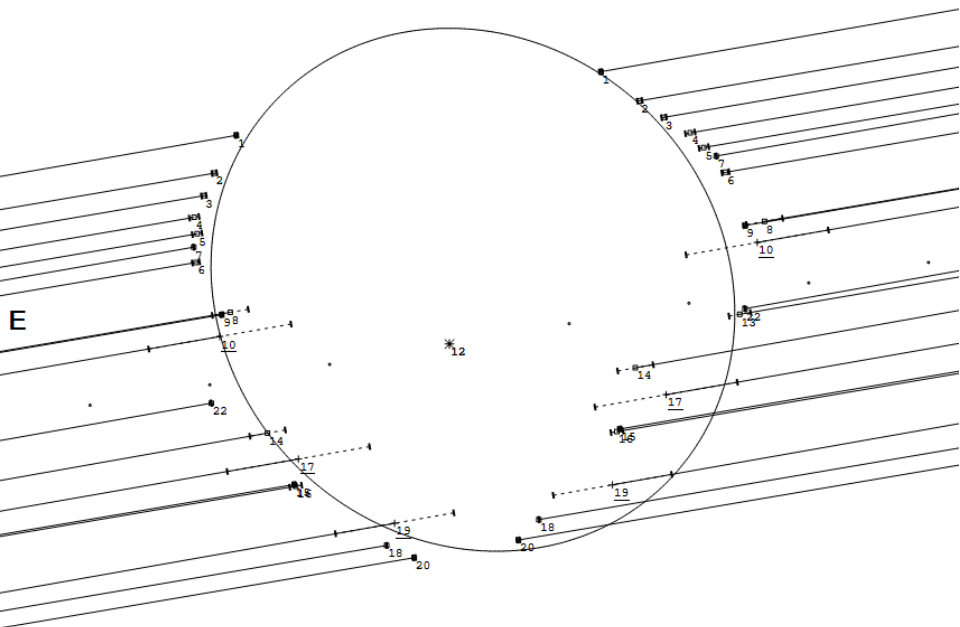
~1.37% Others

Professional CCD,
EMCCD and sCMOS
digital

Bad recording can be catastrophic!

(80) Sappho 2018 Sep 16 70.0 ± 3.5 x 63.9 ± 2.2 km, PA 225.2° ± 26.6°
 Geocentric X -4207.6 ± 0.9 Y 3071.7 ± 1.6 km

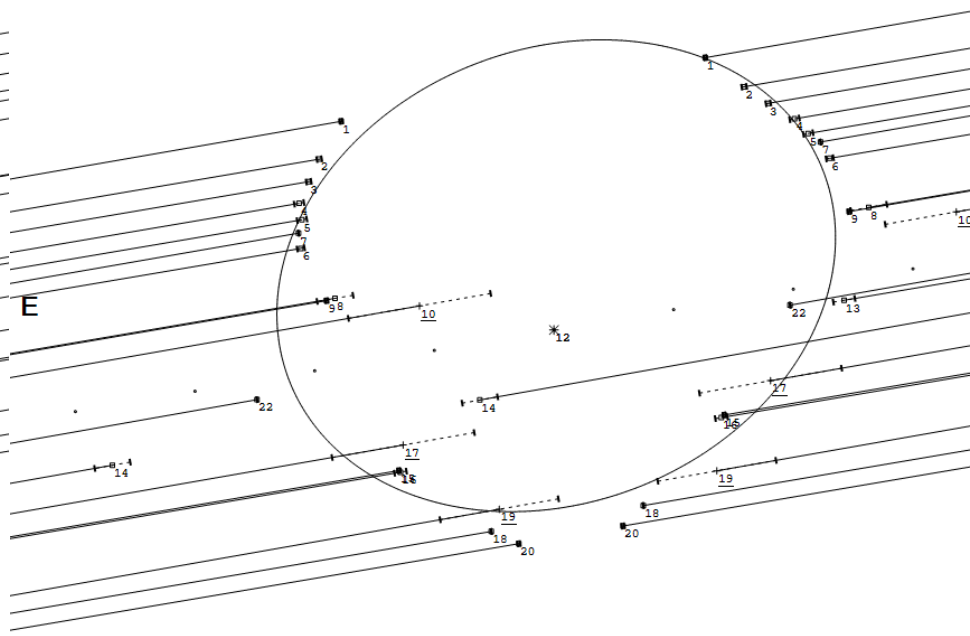
N



Corrected

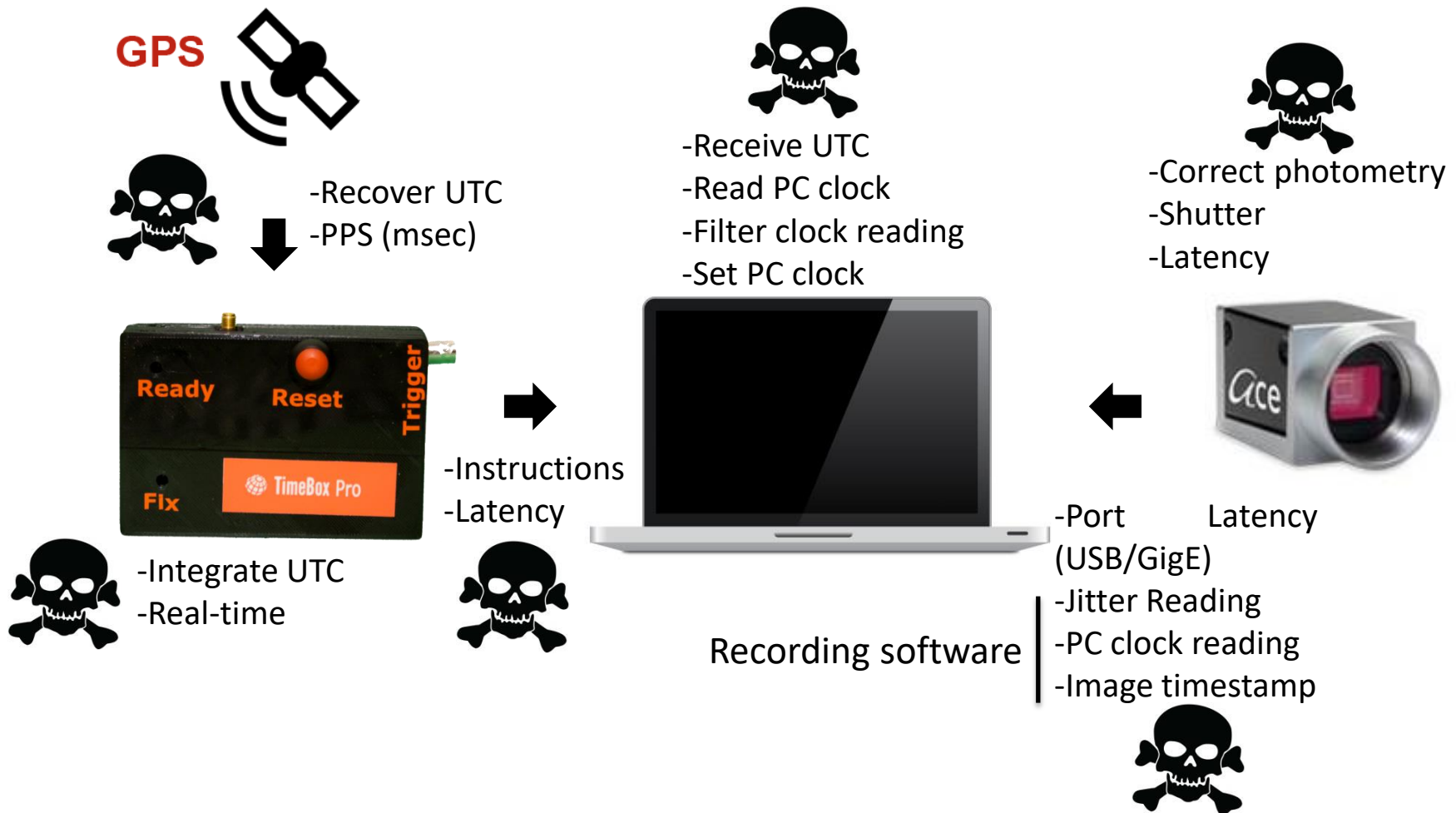
(80) Sappho 2018 Sep 16 73.5 ± 3.7 x 58.1 ± 5.9 km, PA 111.8° ± 28.3°
 Geocentric X -4207.5 ± 1.5 Y 3072.2 ± 2.3 km

N



Original

Occultations with using PC/digital camera



UTC acquisition and timeline

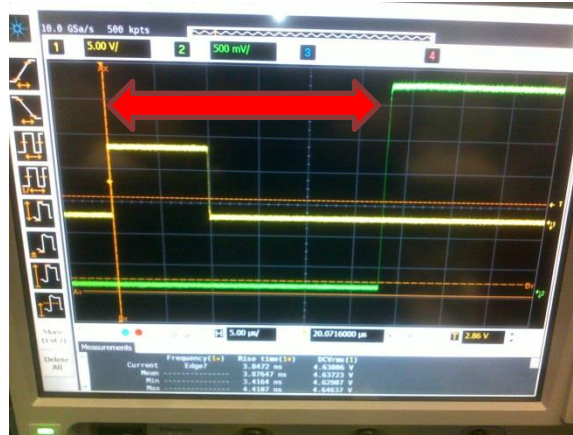
GPS



- Recover UTC
- PPS (msec)



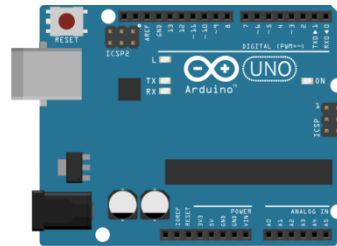
- Integrate UTC
- Real-time



Measure difference SYRTE UTC vs. Device GPS PPS

Results delay of 200 nsec

Arduino integration:



Real Time system

-ATmega328P

Raspberry Pi → OS
Intel Galileo → OS

Occultations using PC/digital cameras



Basler



TIS (DMK)



IDS



ZWO



- Correct photometry
- Shutter
- Latency



Raptor Kite
EMCCD

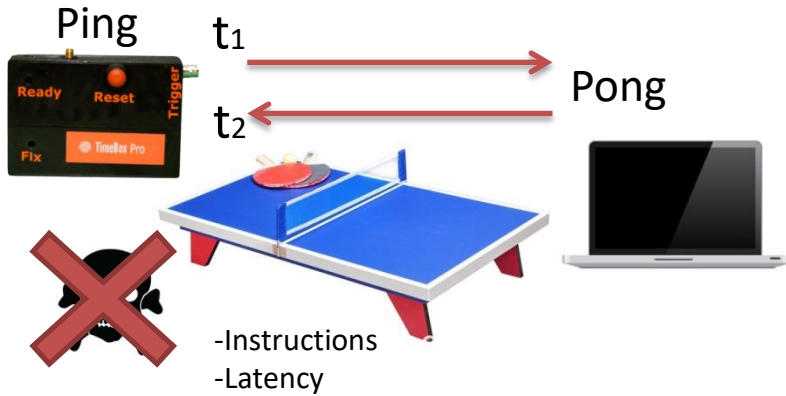


Andor Neo
5.5 sCMOS

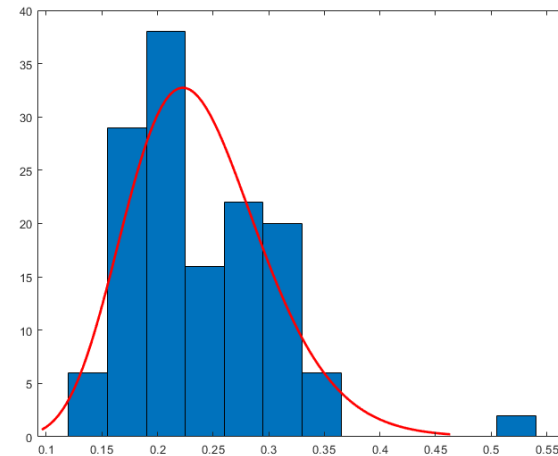
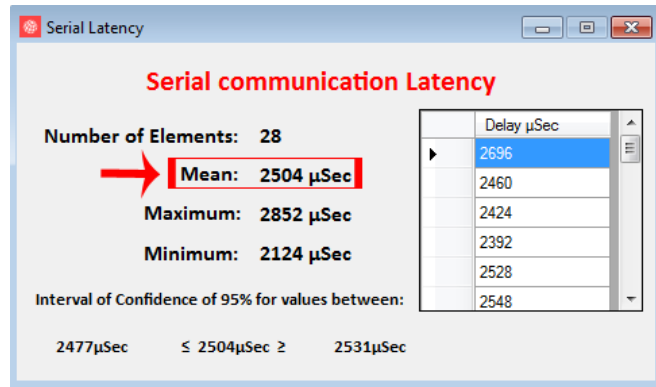


Photonics
Evolve
EMCCD

Dealing with USB serial latency

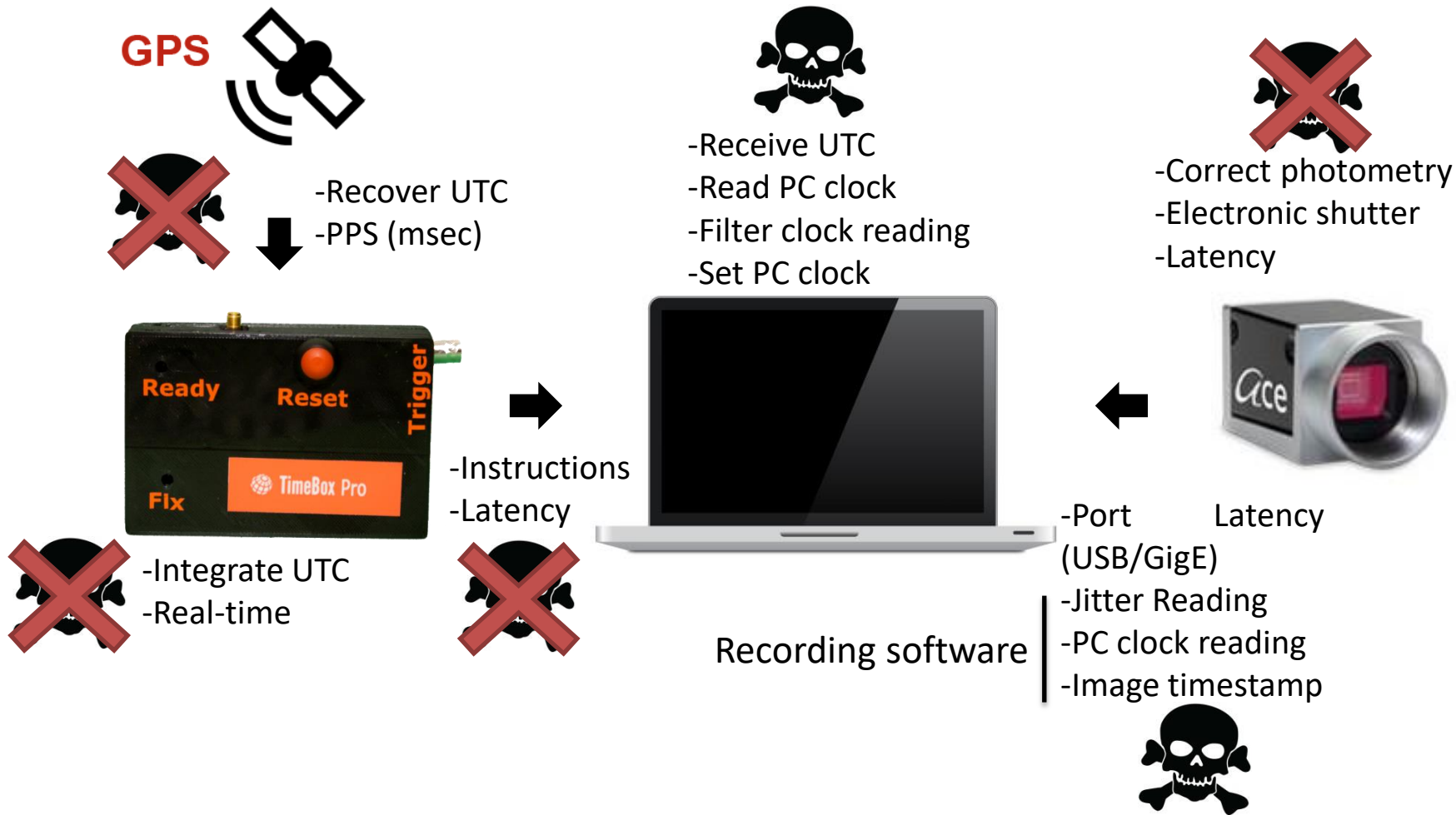


Ping: TimeBox
Pong: AMD FX-8350 4 GHz, USB2 Serial comm.



Median = 2144 μ sec \pm 528 μ sec
Mean = 2383 μ sec \pm 651 μ sec

$$\text{Serial delay} = \frac{t_2 - t_1}{2}$$



Acquiring UTC time in Windows

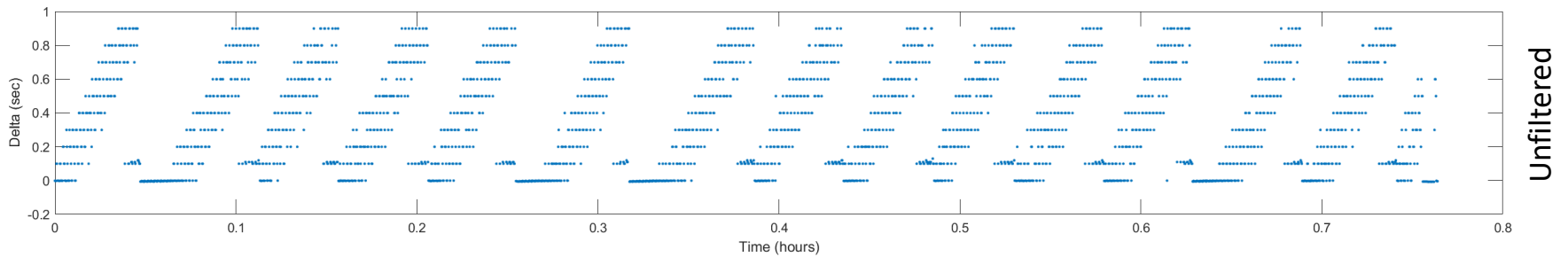
- **GetSystemTime()** Minimum: Windows 2000
Retrieves the current system date and time. The system time is expressed in Coordinated Universal Time (UTC). Resolution 1-2 msec, vary from different systems.
- **GetSystemTimePreciseAsFileTime()** **Minimum: Windows 8**
Retrieves the current system date and time with the highest possible level of precision (<1us). The retrieved information is in Coordinated Universal Time (UTC) format.

Acquiring and filtering UTC timestamps

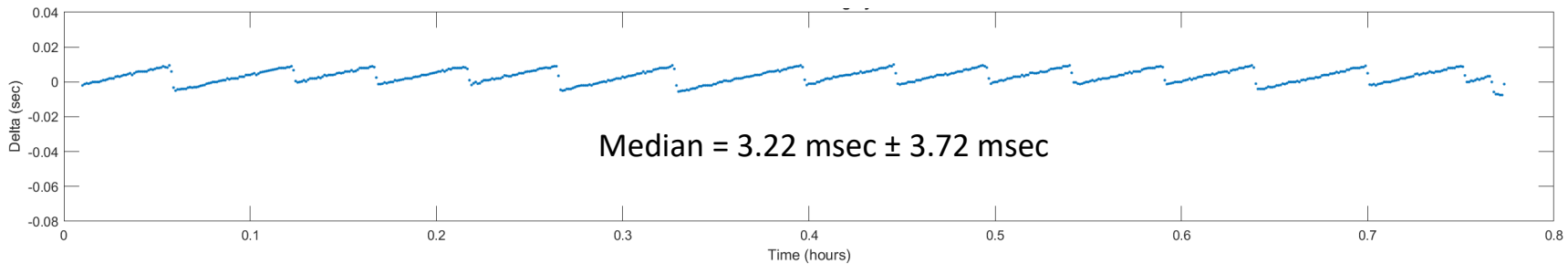


Log file contents:

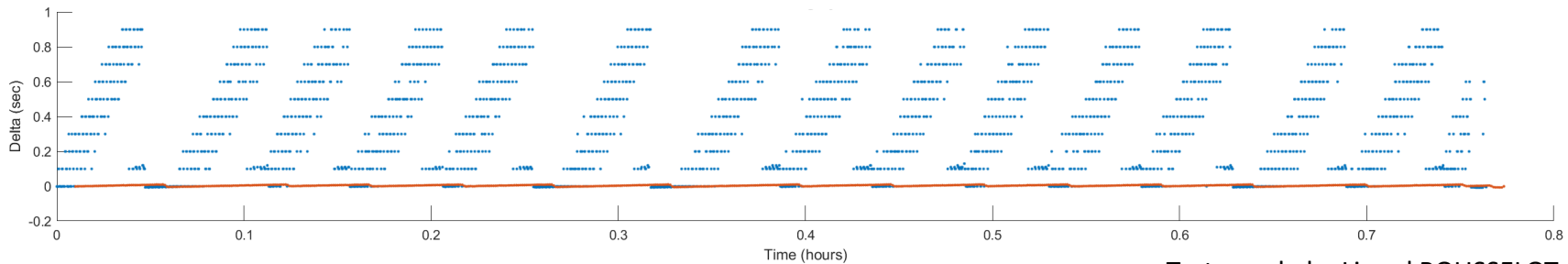
- ✓ RAW timestamp of the PC vs TimeBox
- ✓ Mathematical **filter** of the timestamps → Stable timebase



Unfiltered

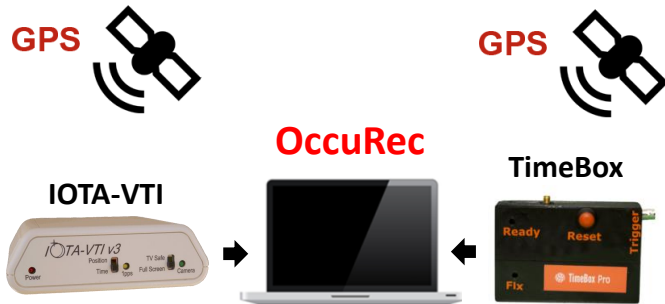


Filtered



Comparison

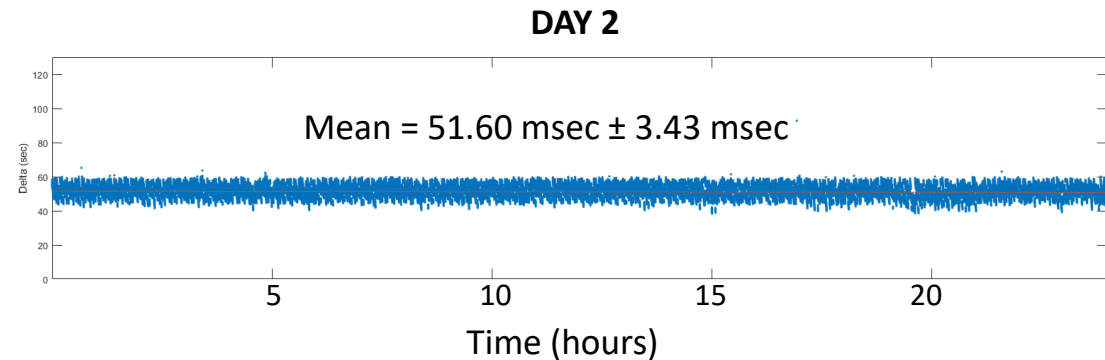
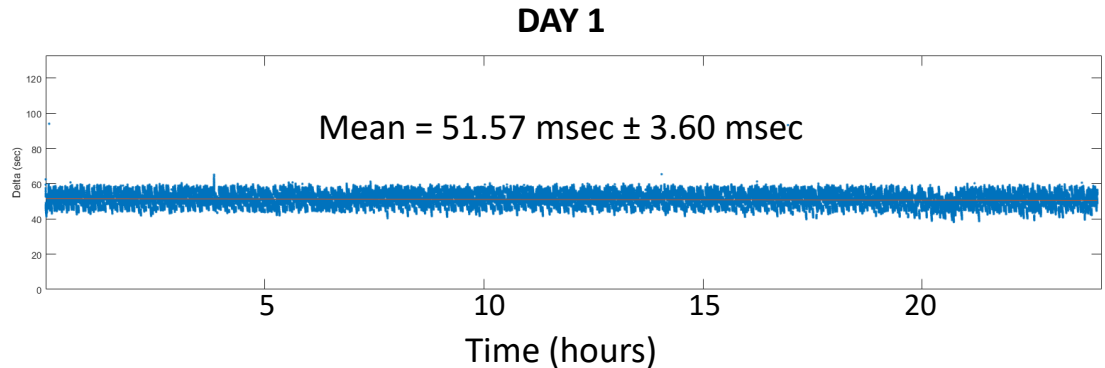
PC time-base for long periods of time



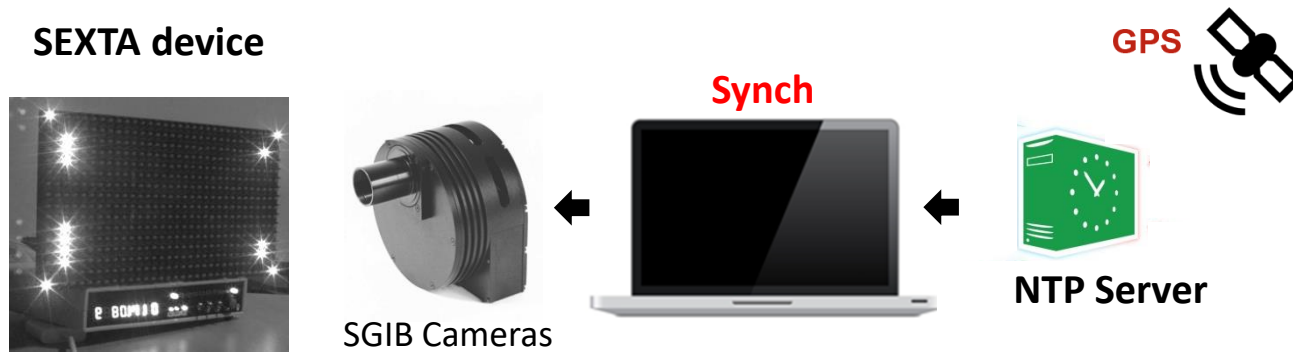
2 million timestamps (25 fps x 24 hours)

Compare the timestamp of the IOTA-VTI frames header vs. the PC clock synchronized with the TimeBox.

- ✓ Constant delay from the Frame grabber
- ✓ Stable timeline for extended periods



Not all recording software are adequate



- **SBIG CCDOPS**



CCDops timestamp resolved to the second.
Average Offset +115 msec with a jitter of -32 to +408 msec

- **SBIG CCDSOFT**



CCDSOFT timestamp resolved to the millisecond.
Average Offset +79 msec with a jitter of ± 17 msec.

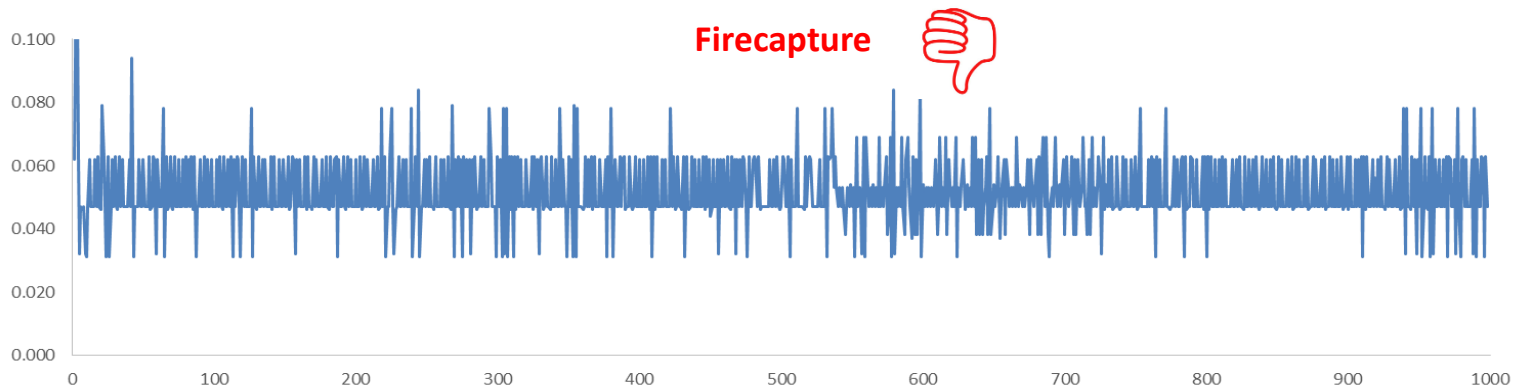
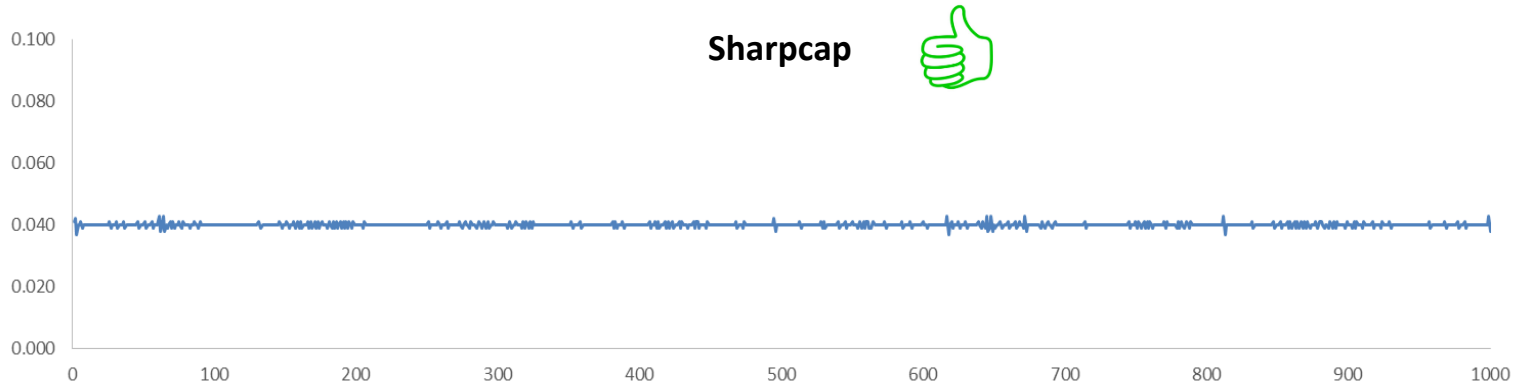
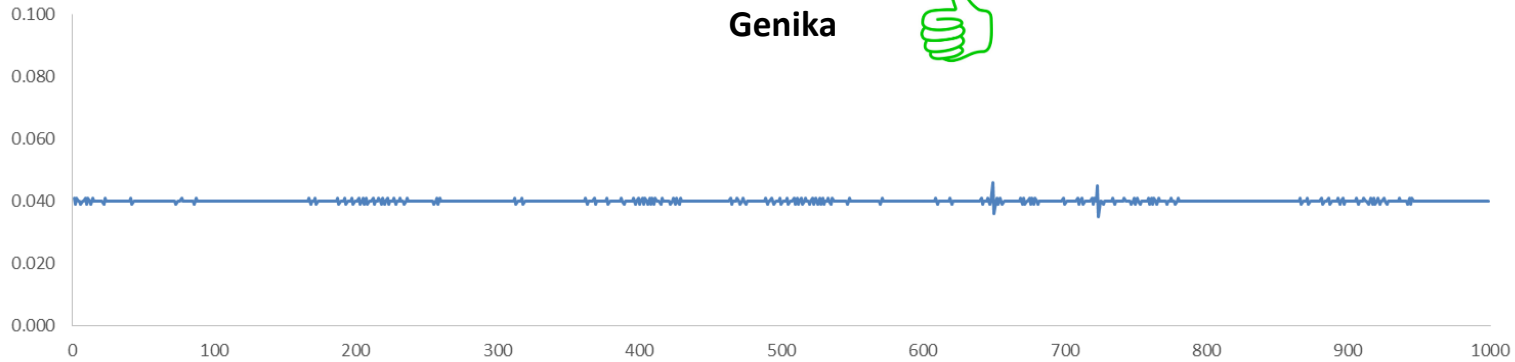
- **MAXIM DL**



MaximDL timestamp resolved to the centisecond.
Average Offset +802 msec with a jitter of ± 20 msec.

Tests by
Tony Barry, Dave Gault *et al.*

Acquisition software is vital for precision

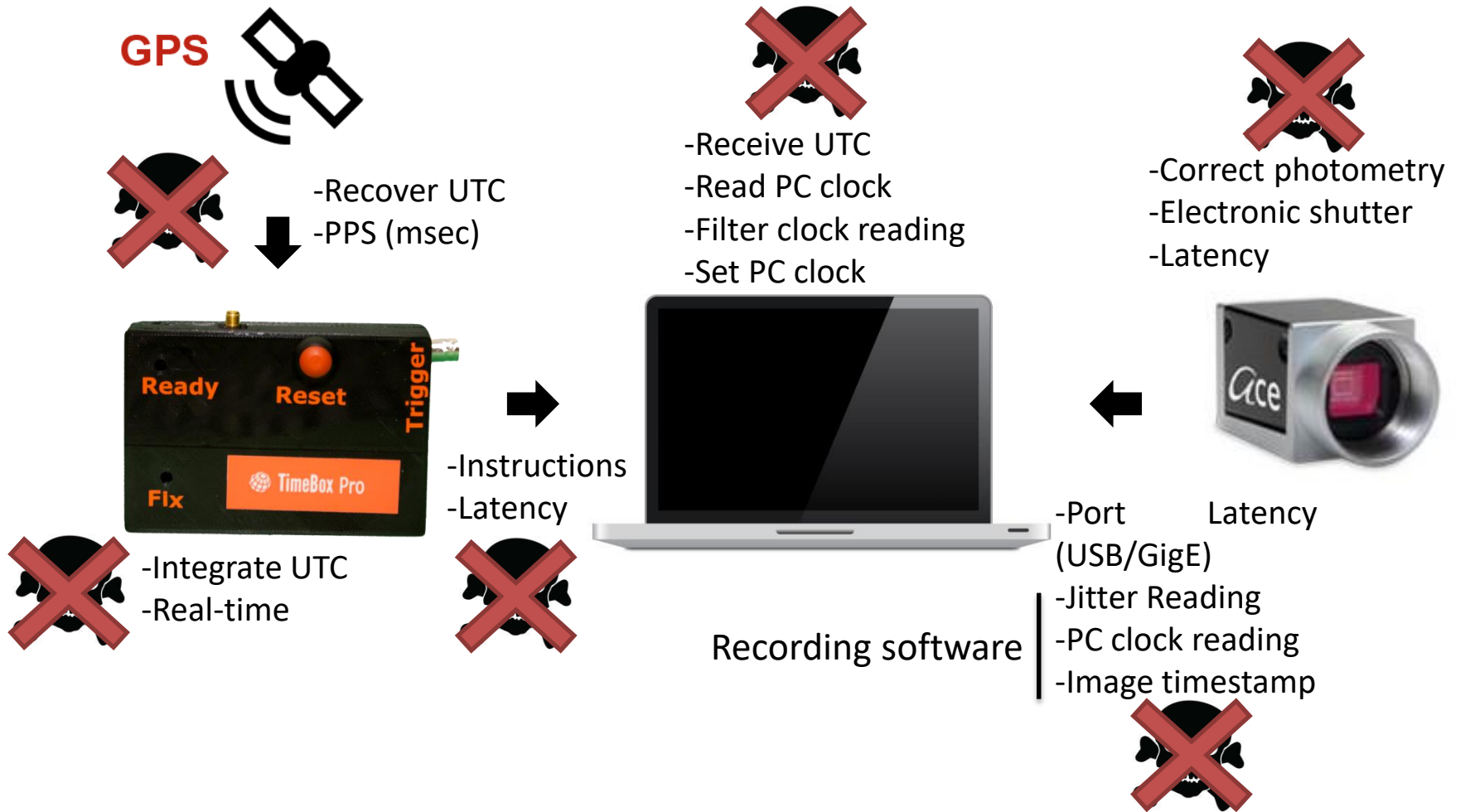


Conditions:

- 1000 images
- Extraction timestamp
- Time between two images

Regularity?

Camera: ZWO 1600
Exposure: 40 msec
No binning
ROI: 1320*1320



Does this work???

IOTA tests with SEXTA device by
Dave GAULT and Hristo PAVLOV

TimeBox vs SEXTA Computer mode

SEXTA device

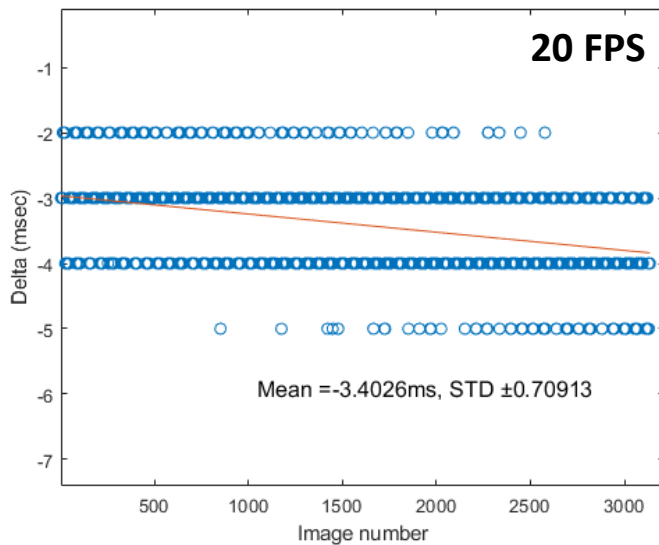


Basler 640-100Gm

Synch
Genika



TimeBox



Exp. time (msec)	FPS	Delay (msec)
14	71	4.65
20	50	3.4
20	50	0.89
40	25	5.58
40	25	1.64
80	13	0.25
100	10	1.74
160	6	3.94
200	5	5.32
320	3	3.83
	Mean	3.12
	STD	1.88

TimeBox vs SEXTA Trigger mode

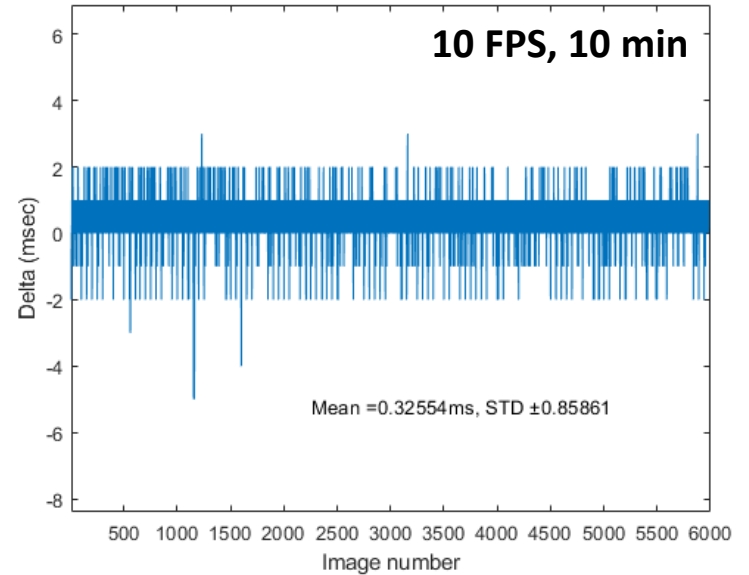
SEXTA device



TimeBox



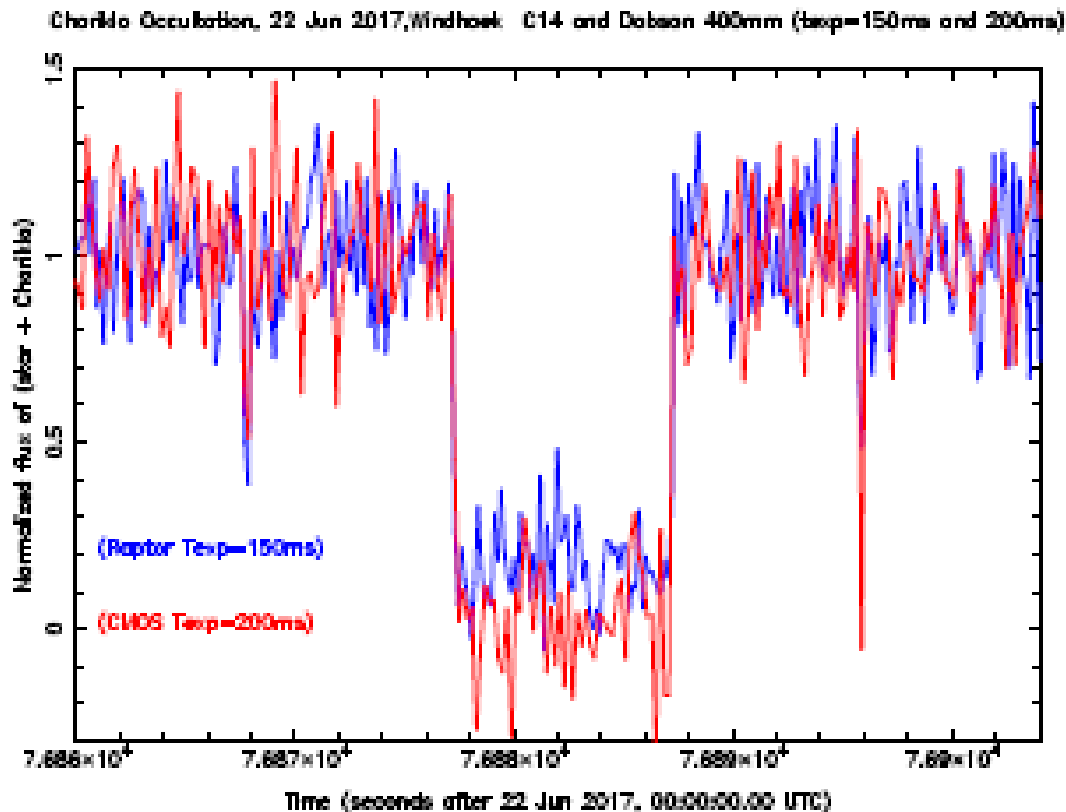
Trigger Genika



Short Tests (< 20 sec)		
FPS	Delay (msec)	STD (msec)
8	0.53	0.74
10	0.03	0.82
15	0.04	0.73
20	0.18	0.98
24	0.38	0.94
	Mean	0.23
	STD	0.11
Long Test (10 min)		
10	0.32	0.85

On the Sky occultations

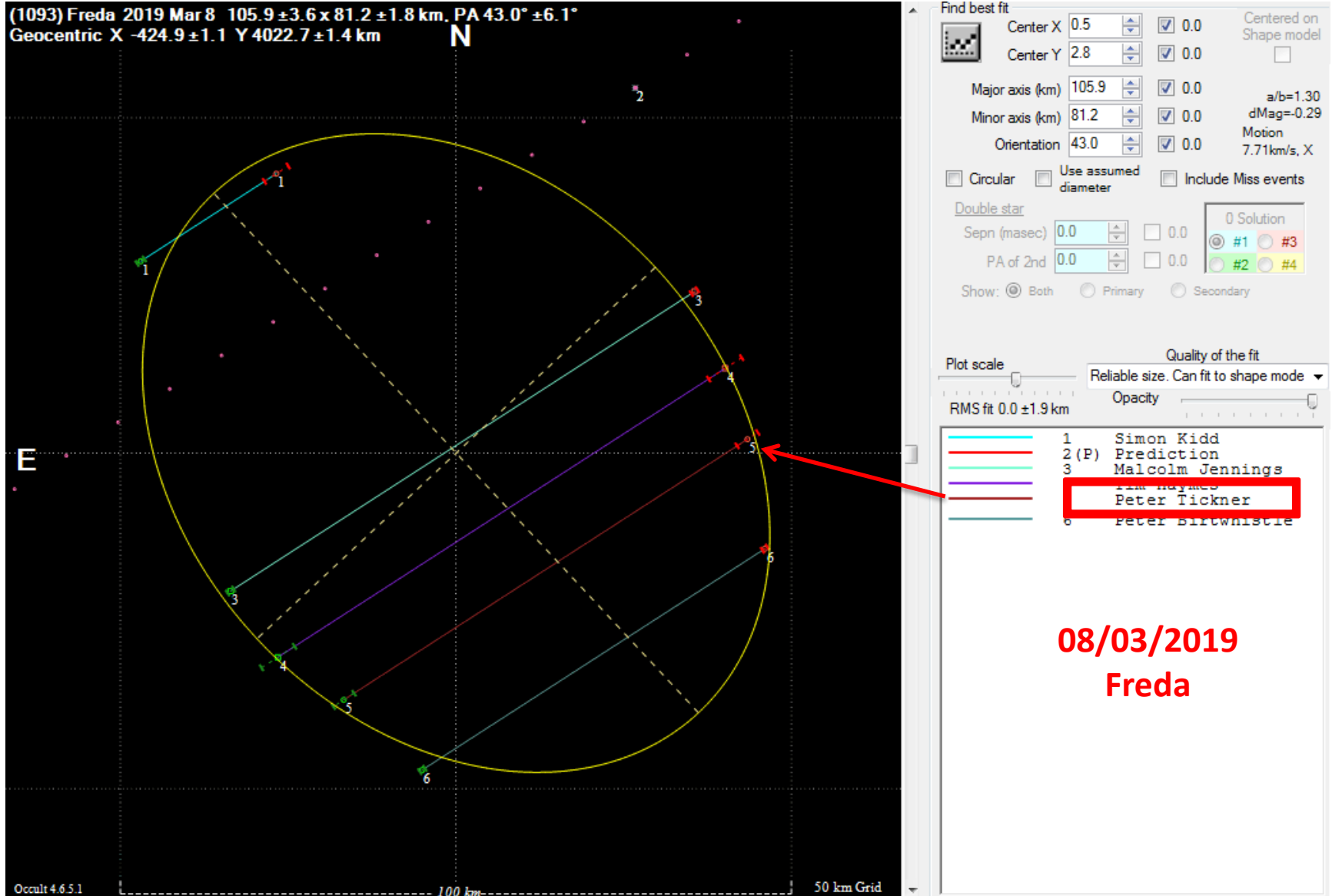
Pr. Bruno SICARDY group, Chariklo 2018



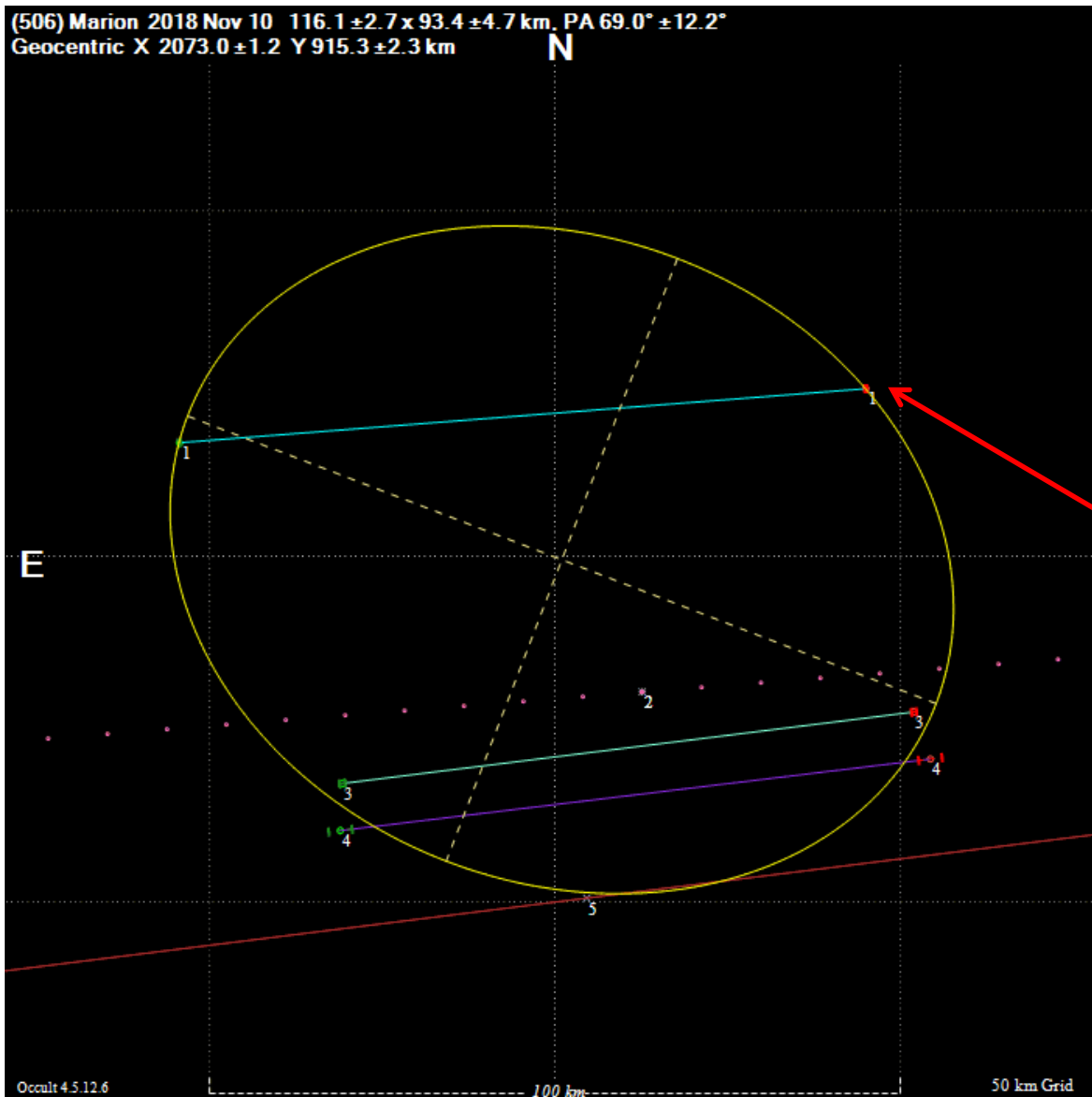
“Figure 3.5: Chariklo light curves observed during 2017. Note the abrupt drops of stellar flux in the case of an airless body like Chariklo. Left: Chariklo occultation light curves observed simultaneously on 2017 June 22 at Windhoek, Namibia. The blue and red light curves correspond to the Raptor Merlin and ZWO Cmos, respectively. It shows the consistency between the absolute time recording systems, down to the 0.1 second level...”

Meza et al. 2018

Peter TICKNER, Freda 2019



Peter TICKNER, Marion 2018



Find best fit

Center X 1.0 0.0
 Center Y 12.1 0.0

Major axis (km) 116.1 0.0
 Minor axis (km) 93.4 0.1
 Orientation 69.0 -0.1

a/b=1.24
 dM=-0.24
 Motion 8.51km/s, X

Double star or double asteroid
 Sepn (masec) 0.0 0.0
 PA of 2nd 0.0 0.0

Show: Both Primary Secondary
 A= 10.0 B= 10.0 PA= 0.0

Circular Include Miss events

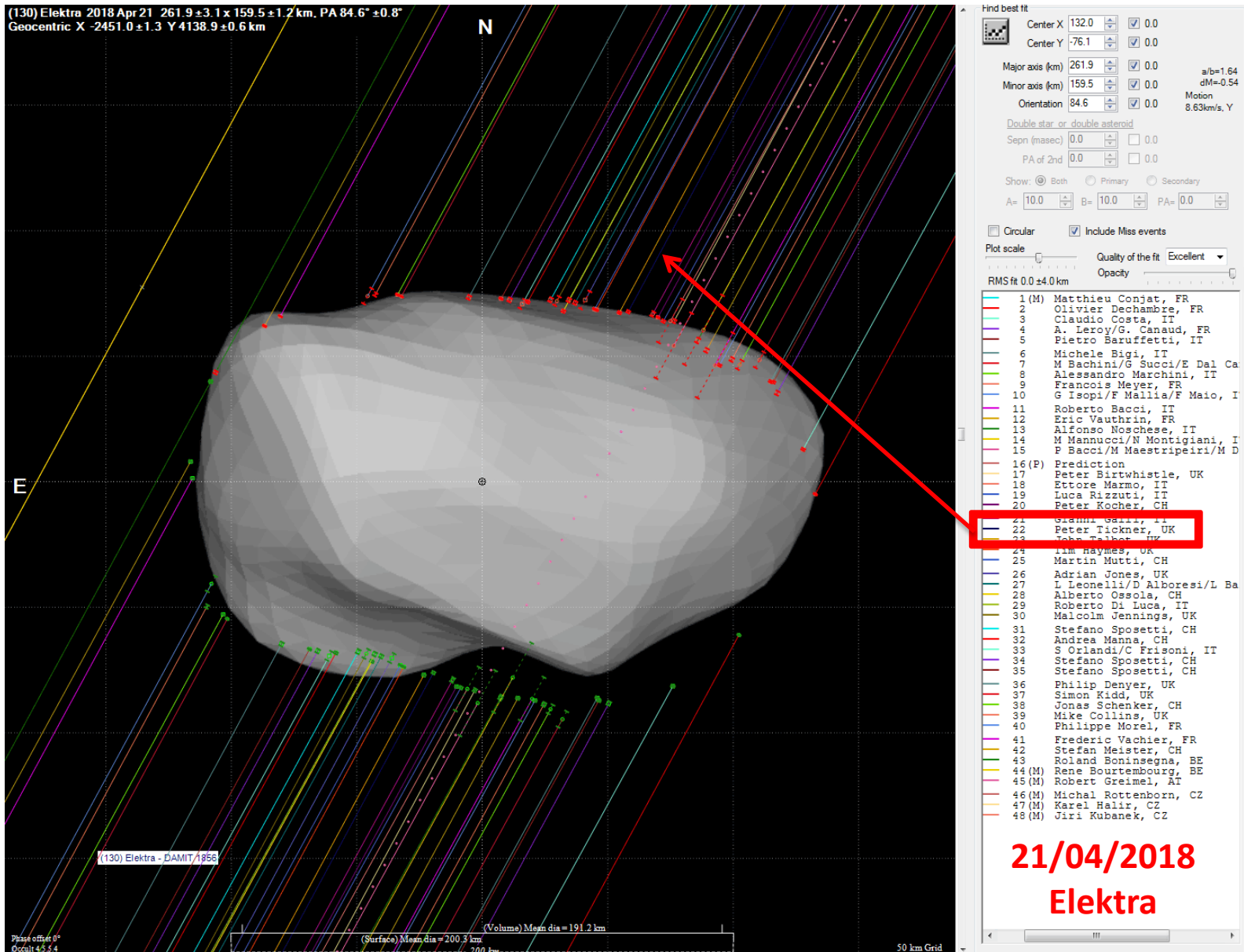
Plot scale Quality of the fit Not fitted
 Opacity

RMS fit 0.0 ± 2.1 km

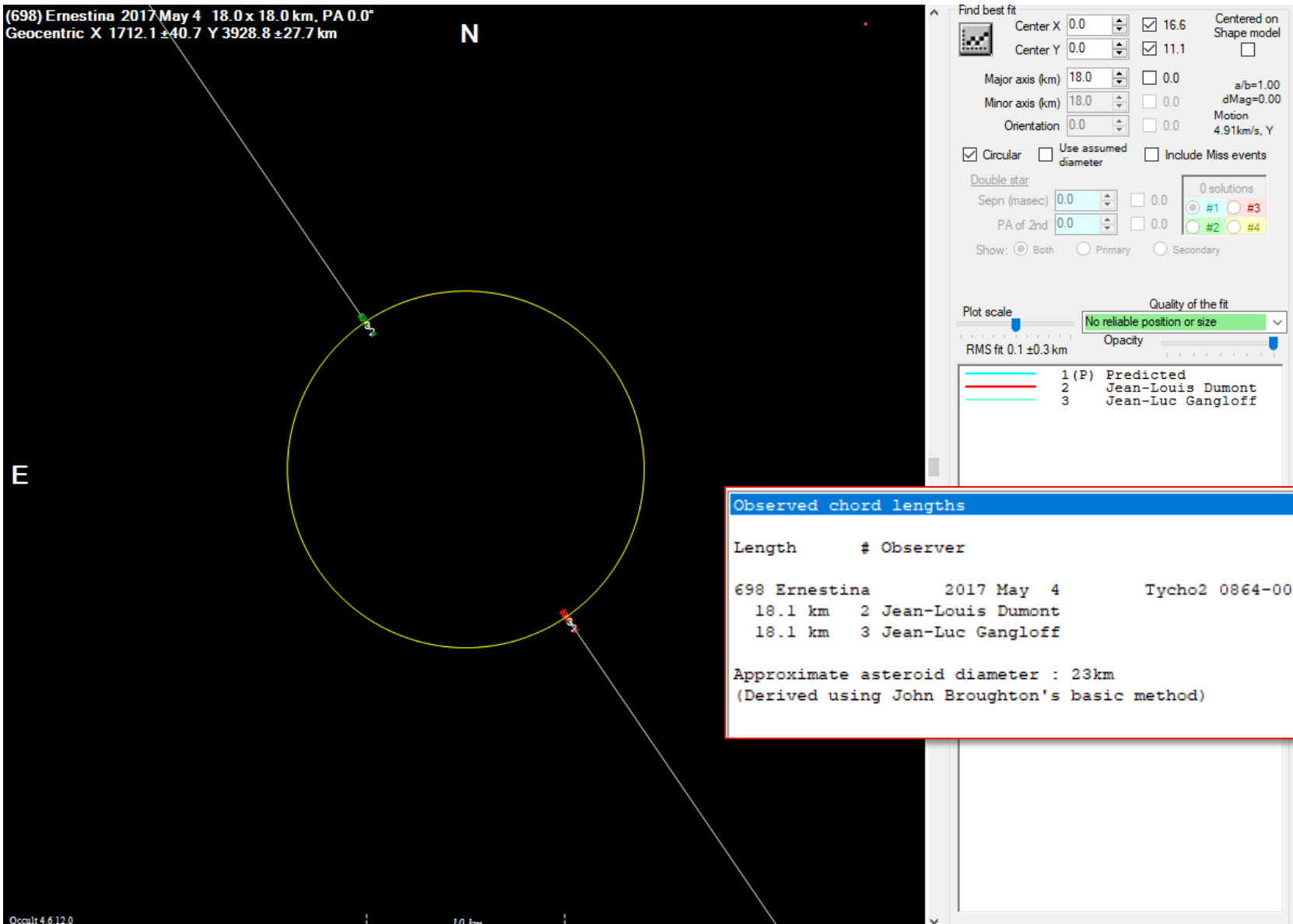
—	1	Peter Tickner, UK
—	3	David Kenyon, US
—	4	Matthew Russell, US
—	5 (M)	Tony George, US

10/11/2018
 Marion

Peter TICKNER, Elektra 2018



Jean-Louis DUMONT, Ernestina 2017



Conclusion: Possible using a PC for occultations

- ✓ Reliable GPS component with precise PPS.
- ✓ Real-time Stratum 1 device to acquire UTC.
- ✓ Calculate Serial latency.
- ✓ Recent CMOS/CCD camera in GigE/USB.
- ✓ Use new Windows PC clock reading method: `GetSystemTimePreciseAsFileTime()`.
- ✓ Mathematical filtering of PC clock.
- ✓ Reliable video recording software.

Thanks for your attention



<http://www.timeBOXutc.com>

info@timeBOXutc.com
sales@timeBOXutc.com